

Reliable <u>High Torque</u> safety clutches for heavy load applications









# Always in use

EAS®-HT safety clutches for heavy load applications prolong the availability of your production systems.

They increase your profit, prevent damage caused by overload and save costs.

## **EAS®-HT** safety clutches

the reliable, non-destructive overload protection

- Disengaging
- Steplessly adjustable
- Precise
- Compact
- Robust





# **Tested safety**

For more than 40 years, we have been dimensioning, developing and manufacturing safety clutches for heavy load applications.

You can rely on the tested reliability and safety of our heavy load clutch.

Experts, not experiments as safety does not allow for compromises





## EAS®-HT short bearing-supported hub



#### Torque: 4 to 40 kNm

Sizes 7 to 10 Type 4050.\_0400

- Direct attachment of the drive element on the bearing-supported, output-side clutch flange.
- The bearing is able to absorb high additional forces in axial and radial directions.

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#### **EAS®-HT lastic**



#### Torque: 4 to 40 kNm

Sizes 7 to 10 Type 4053.\_0400

- Double shaft design with a flexible, positive locking coupling
- Absorbs impact-type loads

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EAS®-HT flange design



# Torque: 7,5 to 440 kNm

Sizes 0 to 6 Type 4060.7\_400

- Compact, ready-to-install module
- Can easily be integrated into the drive line

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**EAS®-HT curved-tooth** 



# Torque: 7,5 to 440 kNm

Sizes 0 to 6 Type 4061.7\_400

- Double shaft design with curved-tooth coupling
- Robust and temperature-resistant
- High misalignment compensation capability

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## EAS®-HT backlash-free



# Torque: 7,5 to 140 kNm

Sizes 0 to 4 Type 4062.704\_0

- Double shaft design with a torsionally rigid, backlash-free disk pack coupling
- High torsional rigidity
- Backlash-free torque transmission
- Maintenance-free

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#### EAS®-HT lastic bolt



#### Torque: 40 to 260 kNm

Sizes 3 to 5 Type 4063.704\_0

- Double shaft design with a flexible, positive locking coupling
- Absorbs impact-type loads

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## **EAS®-HT Options**

Customer-specific designs Low temperature design Alternative shaft connections **ATEX** 

Page 18

#### EAS®-elements

- Standard
- reinforced



- Torque limiting or force limiting elements
- Installation into two flanges located towards one
- Integration into existing constructions possible

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#### **Technical Explanations**

General Pre-selection Misalignment compensation capability Page 23

## Additional branch-optimised EAS® safety clutches

### **High-speed clutches** EAS®-HSE



Torque: 100 to 8.400 Nm

Sizes 02 to 0 Type 404\_ . \_04\_ \_ Reliable overload protection at high speeds

For more information as well as detailed Technical Data and Dimensions, please see our product catalogue EAS®-HSC/ EAS®-HSE.

## **Extruder clutches EAS®-dutytorque**



Torque: 70 to 17.000 Nm

Sizes 2 to 9 Type 4043. \_1400 Protect extruder screws from expensive damage caused by overload

For more information as well as detailed Technical Data and Dimensions, please see our product catalogue EAS®-dutytorque.

### Rustproof design



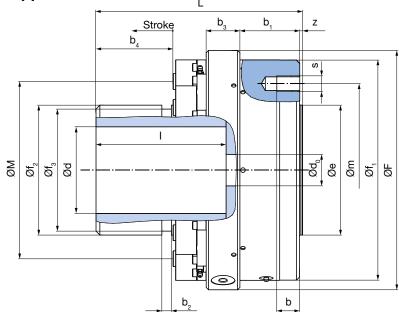


Corrosion-protected safety clutches for environmental and waste water technology



# Short bearing-supported hub

Type 4050.\_0400 Sizes 7 to 10





Orde	Order Number												
/	4	0	5	0 .	_	0	4	0	0	/ _	/		/ _
Sizes 7 to 10	Torque low medium high very hig				4 5 6 7					Bores <sup>1)</sup> Ø d <sup>H7</sup>		Bore Ø d <sub>0</sub>	Torque adjust- ment value [kNm]

Example: Order Number 8 / 4050.60400 / 90 / 35 / 84050.60400 / 90 / 35 / 8

1) Position of the keyway to the tapped hole "s" in the thrust piece is not defined. Defined position available on request.

Technical Dat					Si	ze	
recrimical Dat	Teomina Data				8	9	10
	Type 4050. <b>4</b> 0400	$M_{\scriptscriptstyle G}$	[kNm]	1.3 - 2.6	1.6 - 3.2	4 - 8	5 - 10
	Number of	Number of EAS®-elements			2	2	2
Limit torque	Type 4050. <b>5</b> 0400	$M_{\scriptscriptstyle G}$	[kNm]	2 - 4	3.2 - 6.4	6 - 12	10 - 20
Limit torques for overload	Number of EAS®-elements			3	4	3	4
ioi overioau	Type 4050. <b>6</b> 0400	$M_{\scriptscriptstyle G}$	[kNm]	2.6 - 5.2	4.8 - 9.6	8 - 16	15 - 30
	Number of	Number of EAS®-elements		4	6	4	6
	Type 4050. <b>7</b> 0400	$M_{\scriptscriptstyle G}$	[kNm]	4 - 8	6.5 - 13	12 - 24	20 - 40
	Number of	EAS®-el	ements	6	8	6	8
Sizes EAS®-elements		0	0	1	1		
Maximum speed	Maximum speed n <sub>max</sub> [r		[rpm]	3000	2800	2500	2200
Bolt stroke on ov	erload		[mm]	6	6	8	8

Max. permitte	ed forces on the fla	ange c	on-	Size						
nection				7	7 8 9 10					
Radial forces	Type 40500400	F <sub>R</sub>	[kN]	15	20	30	40			
Axial forces	1ype 40300400	F <sub>A</sub>	[kN]	10	15	20	30			

Mass moments of inertia and weights				Size						
				7	8	9	10			
EAS®-hub side	Type 40500400 J [kgm²]			0.18	0.38	1.05	2.37			
Flange side	Type 40500400	J	[kgm²]	0.17	0.38	1.3	2.65			
Weight at d <sub>max</sub>	Type 40500400		[kg]	47	76	145	232			

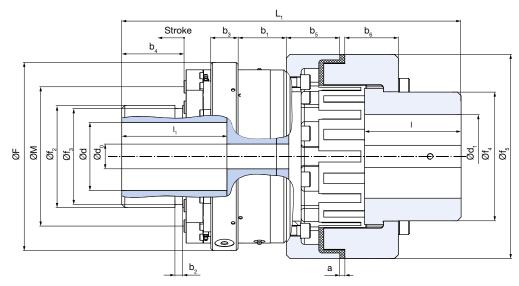
Bores [mm]			Size						
		7	8	9	10				
EAS®-hub side	d <sub>max</sub>	90 <sup>H7</sup>	110 <sup>H7</sup>	135 <sup>H7</sup>	160 <sup>H7</sup>				
Flange side	d <sub>0 max</sub>	30	40	48	58				

We reserve the right to make dimensional and constructional alterations.

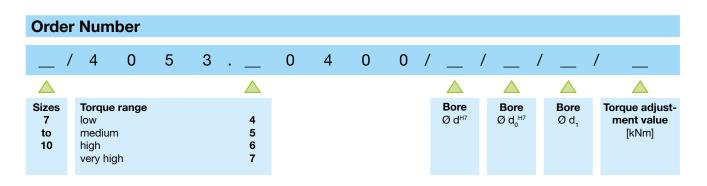
Dimensions		Si	ze	
[mm]	7	8	9	10
b	25	30	35	35
b <sub>1</sub>	66	78	94	110
b <sub>2</sub>	12.5	12.5	15	15
b <sub>3</sub>	44	44	56	56
b <sub>4</sub>	70.5	100.5	119.3	159.3
<b>e</b> <sub>h7</sub>	147	165	242	276
F	260	304	380	450
f <sub>1</sub>	237.5	279.5	359.5	417.5
f <sub>2</sub>	120	165	190	245
f <sub>3</sub>	110	155	180	230
L	228	270	330	387
1	140	170	210	250
M	180	225	270	340
m	190	220	285	325
s	8xM16	8xM20	8xM24	12xM24
z	4	4	5	6



Type 4053.\_0400
Sizes 7 to 10







Example: Order Number 8 / 4053.60400 / 90 / 35 /115 / 8

Tackwisel Det	_				Si	ze	
Technical Dat	.a 			7	8	9	10
	Type 4053. <b>4</b> 0400	o M <sub>G</sub>	[kNm]	1.3 - 2.6	1.6 - 3.2	4 - 8	5 - 10
	Numbe	er of EAS®-	elements	2	2	2	2
	Type 4053. <b>5</b> 0400	) M <sub>G</sub>	[kNm]	2 - 4	3.2 - 6.4	6 - 12	10 - 20
Limit torques for overload	Numbe	Number of EAS®-elements		3	4	3	4
ior overioad	Type 4053. <b>6</b> 0400	4053. <b>6</b> 0400 M <sub>G</sub>		2.6 - 5.2	4.8 - 9.6	8 - 16	15 - 30
	Numbe	er of EAS®-	elements	4	6	4	6
	Type 4053. <b>7</b> 0400	o M <sub>G</sub>	[kNm]	4 - 8	6.5 - 13	12 - 24	20 - 40
	Number of EAS®-elements			6	8	6	8
Sizes EAS®-elem	ents			0	0	1	1
Maximum speed		n <sub>max</sub>	[rpm]	2250	2000	1500	1400
Bolt stroke on ov	verload		[mm]	6	6	8	8
Pl. N.I.	Permitted axia	$\Delta K_a$	[mm]	±2.5	±2.5	±2.5	±2.5
Flexible shaft coupling	misalign- radi	al ∆K <sub>r</sub>	[mm]	0.3	0.3	0.3	0.3
Shart Couping	ments 1) ang	ular ∆K <sub>w</sub>	[mm]	0.3	0.3	0.3	0.3
Nominal and max	ximum torques,	T <sub>KN</sub>	[kNm]	5.8	9.9	20.5	28
flexible coupling		T <sub>K max</sub>	[kNm]	8.3	14.5	27	66

Mass moments of inartia and weights				Size						
Mass moments of inertia and weights			7	8	9	10				
Mass moments of EAS®-hub side		J	[kgm²]	0.18	0.38	1.05	2.37			
inertia	Flexible side	J	[kgm²]	0.57	1.62	5.0	10.7			
Weight at d <sub>max</sub>			[kg]	85	154	282	464			

Bores [mm]			Size							
		7	8	9	10					
EAS®-hub side	d <sub>max</sub>	90 <sup>H7</sup>	110 <sup>H7</sup>	135 <sup>H7</sup>	160 <sup>H7</sup>					
Bearing flange	d <sub>0 max</sub>	30	40	48	58					
Flexible side	d <sub>1 max</sub>	115 <sup>H7</sup>	135 <sup>H7</sup>	180 <sup>H7</sup>	200 <sup>H7</sup>					

Dimensions	Size			
[mm]	7	8	9	10
а	5.5	8	8	8
b <sub>1</sub>	66	78	94	110
b <sub>2</sub>	12.5	12.5	15	15
b <sub>3</sub>	44	44	56	56
b <sub>4</sub>	70.5	100.5	119.3	159.3
<b>b</b> <sub>5</sub>	76	86.5	102	108
b <sub>6</sub>	76	86.5	102	108
F	260	304	380	450
f <sub>2</sub>	120	165	190	245
f <sub>3</sub>	110	155	180	230
f <sub>4</sub>	164	208	275	289
f <sub>5</sub>	265	330	415	480
L,	469.5	548.5	668	754
I	137	156	196	220
I <sub>1</sub>	140	170	210	250
M	180	225	270	340

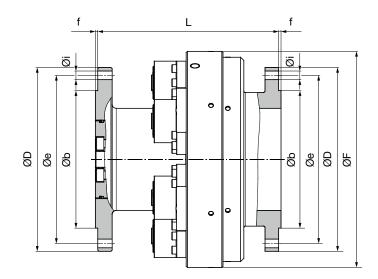
We reserve the right to make dimensional and constructional alterations.

1) The values refer to 1500 rpm.

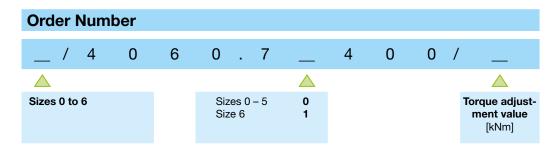


# Flange design

Type 4060.00400 Sizes 0 to 6







Example: Order number 5/ 4060.00400 / 200



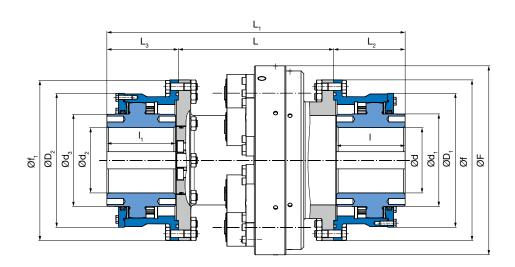
Technical Data			Size							
			0	1	2	3	4	5	6	
Limit torques for overload	$M_{G}$	[kNm]	7.5 - 15	12.5 - 25	20 - 40	37.5 - 75	70 - 140	125 - 250	220 - 440	
Number of EAS®-elements			6	8	6	8	12	10	10	
Sizes EAS®-elements			0	0	1	1	1	2	2 1)	
Maximum speed	n <sub>max</sub>	[rpm]	2000	1750	1500	1250	1000	900	750	
Bolt stroke on overload		[mm]	6	6	8	8	8	12	12	

Mass moments of inertia and weights				Size							
wass moments of mertia and weights			0	1	2	3	4	5	6		
EAS®-element-side	0.25	0.5	1.16	2.71	5.51	16.29	27.87				
EAS®-pressure flange side	0.19	0.37	0.96	2.05	4.22	10.29	19.3				
Weight at d <sub>max</sub>	56	77	142	212	303	627	814				

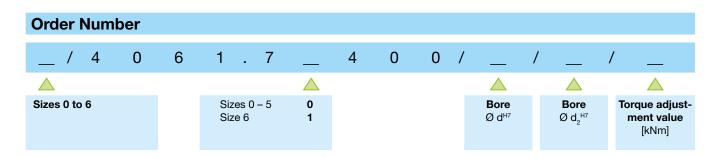
Dimensions	Size										
[mm]	0	1	2	3	4	5	6				
b <sub>h7</sub>	175	230	255	310	340	460	540				
е	214	269	306	360	400	531	618				
D	234	292	330	390	430	567	660				
F	275	320	380	455	545	640	740				
f	3	3	4	4	5	6	6				
i	11	13	13	17	17	21	25				
L	226	243	298	312	328	476	485				

We reserve the right to make dimensional and constructional alterations.

# Curved-tooth Type 4061.00400 Sizes 0 to 6







Example: Order number 4 / 4061.00400 / 180 / 200 / 90

Tooknied D	oto							Size			
Technical D	ala				0	1	2	3	4	5	6
Limit torques f	or overload		$M_{G}$	[kNm]	7.5 - 15	12.5 - 25	20 - 40	37.5 - 75	70 - 140	125 - 250	220 - 440
Number of EAS	®-elements				6	8	6	8	12	10	10
Sizes EAS®-eler	ments				0	0	1	1	1	2	2 1)
Maximum spee	ed		n <sub>max</sub>	[rpm]	2000	1750	1500	1250	1000	900	750
Bolt stroke on	overload			[mm]	6	6	8	8	8	12	12
0	Permitted	axial	$\Delta K_{a}$	[mm]	±2	±3	±3	±3	±3	±4	±4
Curved-tooth coupling	misalign-	radial	$\Delta K_r$	[mm]	7.5	8.6	10.2	11.7	12.4	18.4	20.6
ments 1) 2) angular		$\Delta K_{w}$	[mm]	1.25	1.25	1.25	1.25	1.25	1.25	1.25	
Nominal and maximum torques, $T_{KN}$ [kNm]		12.5	25	40	63	100	250	400			
curved-tooth c	oupling		T <sub>K max</sub>	[kNm]	25	50	80	12.6	200	500	800

The values refer to 1500 rpm.
 Per joint

Mass moments of inertia and weights			Size							
wass moments of inertia and weights		0	1	2	3	4	5	6		
EAS®-pressure flange side	J	[kgm²]	0.27	0.65	1.48	3.33	6.43	19.17	39.74	
EAS®-element side	J	[kgm <sup>2</sup> ]	0.34	0.78	1.69	3.99	7.72	25.18	48.3	
Weight at d <sub>max</sub> / d <sub>2max</sub>		[kg]	83	132	220	345	488	1053	1523	

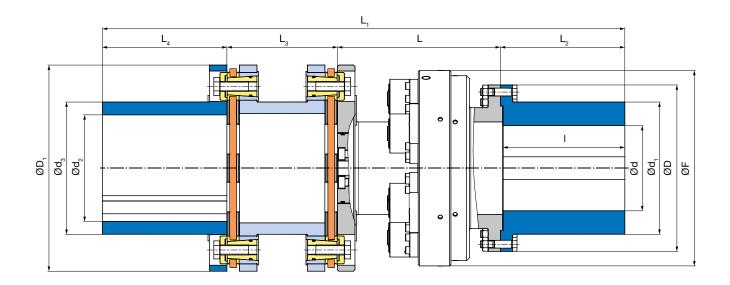
Paras [mm]		Size							
Bores [mm]		0	1	2	3	4	5	6	
EAS®-pressure flange side	d <sub>max</sub>	95	130	150	185	210	285	340	
EAS®-element side	d <sub>2 max</sub>	95	130	150	185	210	285	340	

Dimensions	Size										
[mm]	0	1	2	3	4	5	6				
d <sub>1</sub>	135	185	210	255	290	400	480				
$d_3$	135	185	210	255	290	400	480				
D <sub>1</sub>	195	251	288	337	375	502	584				
$D_{_2}$	195	251	288	337	375	502	584				
F	275	320	380	455	545	640	740				
f	234	292	330	390	430	567	660				
f <sub>1</sub>	234	292	330	390	430	567	660				
L	226	242.5	298	312	328	476	485				
L,	434	502.5	588	685	740	1012	1125				
$L_{\!\scriptscriptstyle 2}$	104	130	145	186.5	206	268	320				
$L_{\scriptscriptstyle{3}}$	104	130	145	186.5	206	268	320				
1	100	125	140	180	200	260	310				
l,	100	125	140	180	200	260	310				

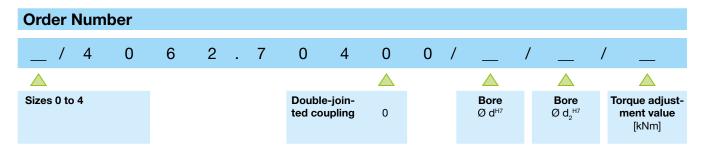
We reserve the right to make dimensional and constructional

## backlash-free

Type 4062.00400 Sizes 0 to 4







Example: Order number 4 / 4062.00400 / 180 / 200 / 90

Technical Dat	-						Size		
Technical Dat	lecillicai Data					1	2	3	4
Limit torques for overload		$M_{\rm G}$	[kNm]	7.5 - 15	12.5 - 25	20 - 40	37.5 - 75	70 - 140	
Number of EAS®-	elements				6	8	6	8	12
Sizes EAS®-eleme	ents				0	0	1	1	1
Maximum speed			n <sub>max</sub>	[rpm]	2000	1750	1500	1250	1000
Bolt stroke on ov	verload			[mm]	6	6	8	8	8
<b>T</b>	Permitted	axial	$\Delta K_{a}$	[mm]	1.6	1.7	2.1	2.3	2.3
Torsionally rigid shaft coupling	misalign-	radial	$\Delta K_r$	[mm]	1.0	1.0	1.1	1.3	1.4
ments 1) angular		$\Delta K_{w}$	[°]	0.4	0.4	0.4	0.4	0.4	
Nominal and maximum torques, $T_{KN}$ [kNm]		22	33	50	73	110			
torsionally rigid a	all-steel cou	pling	T <sub>K max</sub>	[kNm]	44	66	100	146	220

<sup>1)</sup> The values refer to 1500 rpm.

Mass moments of inertia and weights						Size		
Mass moments of inertia and weights			0	1	2	3	4	
Mass moments of	Hub-side	J	[kgm²]	0.35	0.76	1.58	3.68	6.56
inertia	Flexible side	J	[kgm²]	0.86	1.73	3.5	7.1	13.95
Weight at d <sub>max</sub>			[kg]	132	195	308	468	665

Boros [mm]				Size		
Bores [mm]		0	1	2	3	4
Hub side	d <sub>max</sub>	120	170	180	220	240
Flexible side	d <sub>2 max</sub>	140	160	180	210	240

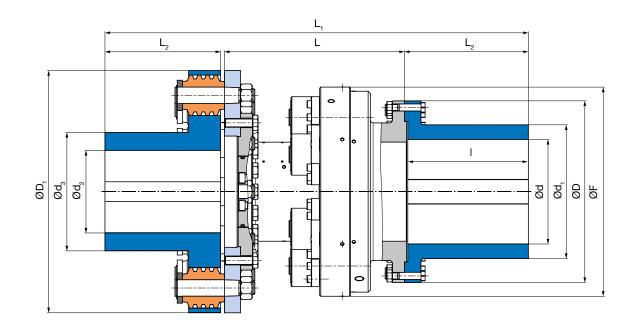
<b>Dimensions</b>			Size		
[mm]	0	1	2	3	4
d <sub>1</sub>	186	230	243	300	321
$d_{_3}$	186	215	243	279	321
D	234	292	330	390	430
D <sub>1</sub>	290	332	378	431	492
F	275	320	380	455	545
L	229	245.5	302	316	330
L,	735	811.5	934	1054.5	1173
$L_{\scriptscriptstyle 2}$	175	200	225	265	310
L <sub>3</sub>	155.6	166	182	208.4	223
L <sub>4</sub>	175	200	225	265	310
ı	171	195	219	260	302

We reserve the right to make dimensional and constructional alterations.

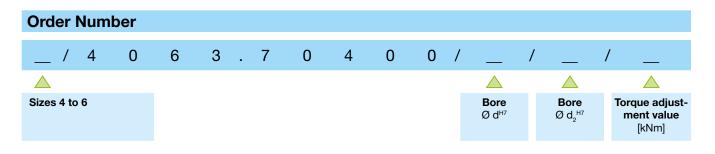
lastic bolt

Type 4063.00400

Sizes 4 to 6







Example: Order number 4 / 4063.00400 / 270 / 180 / 90

Technical Da	la.					Size	
rechnical Da	la				4	5	6
Limit torques for overload		$M_{G}$	[kNm]	40 - 80	72.5 - 145	130 - 260	
Number of EAS®-	elements				12	10	10
Sizes EAS®-elem	ents				1	2	2
Maximum speed	I		n <sub>max</sub>	[rpm]	1000	900	750
Bolt stroke on o	verload			[mm]	8	12	12
Plantin.	Permitted	axial	$\Delta K_{a}$	[mm]	±4	±4	±4
Flexible shaft coupling	misalign-	radial	$\Delta K_r$	[mm]	1.5	1.5	1.5
ments 1) angular		$\Delta K_{w}$	[mm]	4.6	5.3	6.4	
Nominal and ma	Nominal and maximum torques,		$T_{KN}$	[kNm]	48	100	160
flexible coupling			T <sub>K max</sub>	[kNm]	96	200	320

Mass maman	Mass moments of inartia and weights				Size				
Mass moments of inertia and weights				4	5	6			
Mass moments	of Hub-side	J	[kgm²]	6.6	20.02	39.63			
inertia	Flexible side	J	[kgm <sup>2</sup> ]	22.35	55.18	110.68			
Weight at d <sub>max</sub>			[kg]	706	1407	1956			

Paras [mm]			Size					
Bores [mm]		3	4	5				
Hub side	d <sub>max</sub>	240	300	340				
Flexible side	d <sub>2 max</sub>	225	225	320				

<b>Dimensions</b>	Size				
[mm]	4	5	6		
d <sub>1</sub>	321	420	500		
$d_{\scriptscriptstyle{3}}$	320	360	448		
D	430	567	660		
D <sub>1</sub>	660	760	920		
F	545	640	740		
L	375	533	543		
L,	946	1201	1231		
$L_{\!\scriptscriptstyle 2}$	310	350	370		
L <sub>3</sub>	250	300	300		
I	302	342	362		

We reserve the right to make dimensional and constructional alterations.

<sup>1)</sup> The values refer to 1500 rpm.

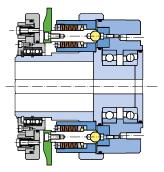
## **EAS®-HT Options**

For the EAS®-HT clutches, designs specially created according to customer requests and different variants are also available.

EAS®-HT clutches can be combined with additional attachment parts.

We are happy to advise you on the dimensioning and configuration of your optimum design.

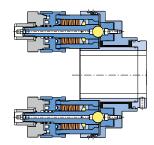
# EAS®-HT with automatic re-engagement



After overload occurrence, the EAS®-HT safety clutch is disengaged. It is possible to engage the EAS®-HT safety clutch via remote control by means of automatic re-engagement. Re-engagement can be carried out pneumatically, hydraulically, electromechanically or mechanically.



#### EAS®-HT with mechanical disengagement

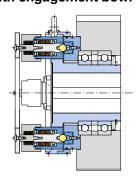


Mechanical disengagement device for the EAS®-elements.

The EAS $^{\otimes}$ -elements can be disengaged individually mechanically.



## EAS®-HT with engagement bowl

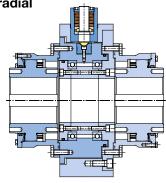


Engagement without aids.

Automatic engagement device for low operating speeds. Direct overload query possible through switching disk.



EAS®-HT radial



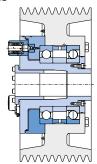
EAS®-HT radial for small construction space length values and low to medium operating speed values.





# **EAS®-HT Options**

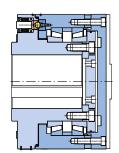
# EAS®-HT with integrated drive elements



EAS®-HT, integrated attachment of sprocket and toothed wheels, V-belt disks etc.



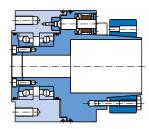
## EAS®-HT for roller gears



Highest torques at lowest diameters. The alternative to hydraulic clamping sets and shear pins in rolling mills.



## Frictionally-locking shaft-hub connection



## Frictionally-locking shaft-hub connections:

- Shrink disk (see Fig.)
- External shrink disk
- Oil press fit

## EAS®-HT low temperature design



# Reliable overload protection in case of very low temperatures to -48 °C.

(Please contact the manufacturer separately for this).



## ATEX design



EAS®-HT safety clutches are also available in ATEX design according to the directive 94/9 EC (ATEX 95).

(Please contact the manufacturer separately for this).



## **EAS®-element**

## **Application**

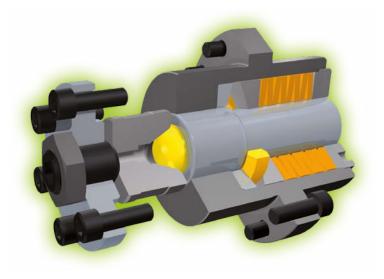
- □ EAS®-elements for installation in two bearingsupported flanges facing each other or for integration into existing constructions
- ☐ As EAS®-HT safety clutch component
- ☐ For customer-specific constructions

## **Applications**

- □ Conveyor belts
- □ Crushers
- □ Rolling mills
- ☐ Underground mining / mining
- □ Raw material extraction

## Advantages/Benefits

- ☐ Safe overload protection
- ☐ Can be used flexibly and in modular form
- ☐ Maximum performance density
- ☐ Release forces adjustable
- □ Easy and quick engagement
- ☐ Large number of disengagement procedures





Rustproof design available on request

#### **Function:**

Positive locking transmission of circumferential force and axial force. In case of overload, the EAS®-elements separate the input and output mechanically, so that the system can slow down freely. Manual re-engagement of the individual elements (automatic reengagement available on request).



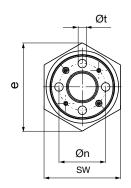
The catalogue contains basic information on pre-selection and dimensioning.

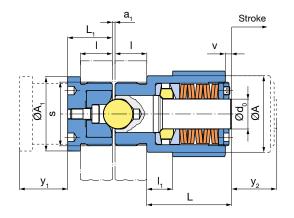
For detailed information on selection, dimensioning, installation, initial operation and maintenance, please see the Installation and Operational Instructions.

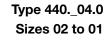


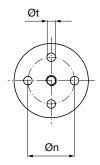
# **EAS®-element**

## **Standard**

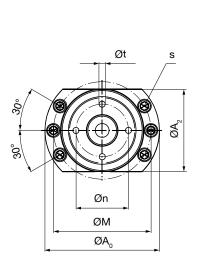


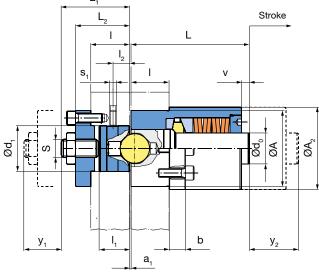


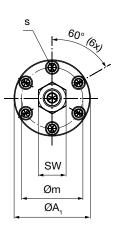




Type 440.\_04.0 Sizes 0 to 2

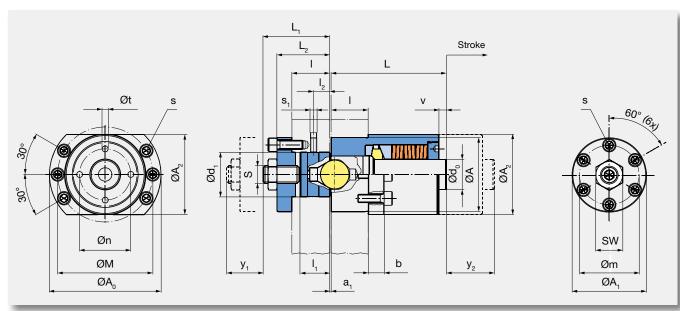






## Reinforced

Type 441.604.0 Sizes 0 to 2



# **EAS®-element**

Technical Data				Size				
			02	01	0	1	2	
	Type 440.404.0 (Low torque range)	F <sub>u min</sub>	[kN]	0,22	1	1.8	5	4
		F <sub>u max</sub>	[kN]	0.54	2	5	10	11
	Type 440.504.0 (Medium torque range)	F <sub>u min</sub>	[kN]	0.5	1.25	3.75	7.5	10
Circumferential		F <sub>u max</sub>	[kN]	1.4	2.5	7.5	15	30
force	Type 440.604.0 (High torque range)	F <sub>u min</sub>	[kN]	1.2	2.5	7.5	15	30
		F <sub>u max</sub>	[kN]	2.5	5	15	30	60
	Type 441.604.0 Reinforced design	F <sub>u min</sub>	[kN]	-	-	19	38	75
		F <sub>u max</sub>	[kN]	-	-	38	75	150
	Type 440.404.0 (Low torque range)	F <sub>ax min</sub>	[kN]	0.2	0.9	1.62	4.5	3.6
Axial force		F <sub>ax max</sub>	[kN]	0.48	1.8	4.5	9	9.9
	Type 440.504.0 (Medium torque range)	F <sub>ax min</sub>	[kN]	0.45	1.12	3.37	6.75	9
		F <sub>ax max</sub>	[kN]	1.26	2.25	6.75	13.5	27
	Type 440.604.0 (High torque range)	F <sub>ax min</sub>	[kN]	1.08	2.25	6.75	13.5	27
		F <sub>ax max</sub>	[kN]	2.25	4.5	13.5	27	54
	Type 441.604.0 Reinforced design	F <sub>ax min</sub>	[kN]	-	-	10	20	40
		F <sub>ax max</sub>	[kN]	-	-	20	40	80
Bolt stroke on overload [mm]		[mm]	2.5	4	6	8	12	
Weights [kg]		[kg]	0.25	0.6	1.75	4.1	11.3	

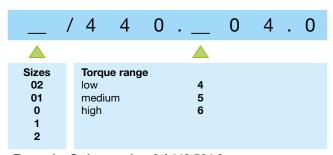
<b>Dimensions</b>			Size		
[mm]	02	01	0	1	2
A H8	28	38	55	75	100
A <sub>o</sub>	-	-	85	110	150
A <sub>1</sub>	28	35	55	75	100
A <sub>2</sub>	-	-	55	75	108
a <sub>1</sub>	1.0	1.5	2	2	3
b	-	-	12	15	20
d <sub>o</sub>	10	14	20	30	40.6
d <sub>1 h7</sub> H8	-	-	30	40	60
е	31.2	41.6	-	-	-
L	28	40	73	96	160
L,	15	21	52	65	80
$L_{\scriptscriptstyle 2}$	-	-	42	51	70
1	12	15	30	40	50

Dimensions			C:		
			Size		_
[mm]	02	01	0	1	2
I,	7	10	22	30	40
	-	-	12	17	22
М	-	=	72	95	128
m	-	-	44	60	80
n	17	22	31	48	69
s	-	-	M12	M20	M24
s	M24x1 1)	M30x1.5 2)	M6 <sup>3)</sup>	M8 <sup>4)</sup>	M12 <sup>5)</sup>
S <sub>1</sub>	-	-	M5	M6	M8
sw	27	36	19	30	36
t	3	4	5	6	8
v	2	3	3	4	15
У <sub>1</sub> <sup>6)</sup>	12	15	8	10	10
<b>y</b> <sub>2</sub> <sup>6)</sup>	16	21	38	50	65

We reserve the right to make dimensional and constructional alterations.

#### **EAS®-element Standard**

## **Order Number**



Example: Order number 0 / 440.504.0

- 1) Tightening torque  $M_A = 40 \text{ Nm}$ 2) Tightening torque  $M_A = 60 \text{ Nm}$
- 3) Fixing screw DIN EN ISO 4762 10.9  $M_{\Delta} = 9 \text{ Nm}$

#### **EAS®-element Reinforced**

## **Order Number**

1 . 6 0 4.0 / 4 4

Sizes

0 1

2

## Example: Order number 0 / 441.604.0

- 4) Fixing screw DIN EN ISO 4762 10.9  $M_A = 19 \text{ Nm}$
- 5) Fixing screw DIN EN ISO 4762 10.9  $\overrightarrow{MM}_A = 76 \text{ Nm}$
- 6)  $y_1$  and  $y_2$  are extension dimensions

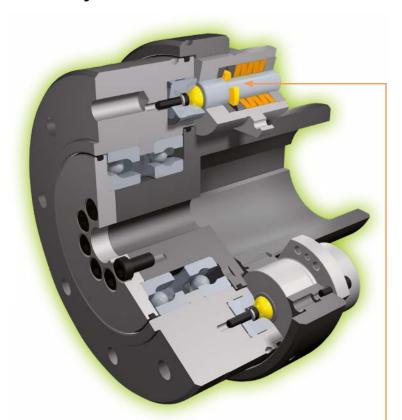


#### **Characteristics**

- ☐ Positive locking torque transmission acc. to the ball-detent principle
- ☐ Adjustable torque
- □ Separates disengagingly
- ☐ Easy repeat operation start-up
- ☐ Robust
- □ Long service lifetime



Rustproof design available on request



#### Design

All clutch parts are made of steel. EAS®-HT safety clutch basic components have a zinc-phosphated surface which provides a basic corrosion protection for further surface treatments.

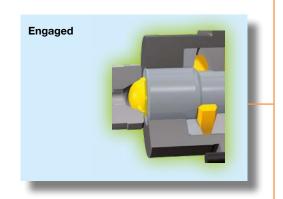
Clutch types 4050, 4060 are also suitable for oil-running.

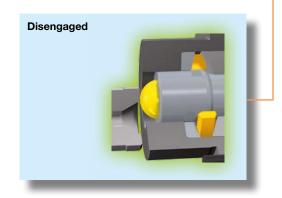
The limit torque for overload on the clutch can be adjusted by changing the cup spring pre-tension of each overload element.

The EAS®-HT safety clutches can be set to the required limit torque for overload at the place of manufacture. Subsequent torque changes can be carried out using the Adjustment Diagram included in the delivery (see respective Installation and Operational Instructions).

### Operating principle of the EAS®-HT safety clutch Overload elements

- ☐ If the proportional circumferential force on the individual elements proves too large, the resulting axial force causes an axial movement of the bolt via the ball/calotte system and therefore the disconnection of the torque transmission.
- ☐ The maximum circumferential force is individually determined through the adjusting nut and *mayr*®-cup springs. The transmittable torque is determined in this way.
- Due to the axial stroke of the bolt (ball carrier), the control segments move radially outwards, thereby disconnecting the components axially.
- ☐ Re-engagement of the balls through a bolt stroke in the direction of the calotte takes place either manually or via a mayr® re-engagement device (pneumatic, hydraulic, electromechanical or mechanical).







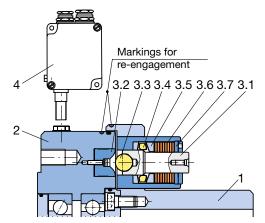
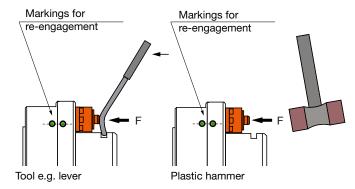


Fig. 2: EAS®-element clutch disengaged

# Processes for torque switch-off on overload:

On overload, the hub part 1 and the output flange 2 begin to turn against each other. The bolts 3.1 in the overload elements are pressed via the control segments 3.4 against the force of the cup springs 3.6 from the thrust washers 3.2. The control segments 3.4 travel radially outwards over the bolt 3.1 switching edge and hold the bolts 3.1 in a disengaged position (see Fig. 2). The positive locking connection of the hub part 1 and the output flange 2 is nullified. The originally coupled masses can slow down freely. The drive is switched off electrically via speed monitoring device 4.



Re-engagement:
Turn the hub part 1 and

Turn the hub part 1 and the output flange 2 into the correct angular position to one another (re-engagement position can be recognized via the marking bores on the clutch outer diameter, Fig. 3). By applying axial pressure on the bolt end, bolts 3.1 are brought back to their engaged position. The clutch is ready for operation when all clutch overload elements are engaged.

Fig. 3

#### **Maintenance**

The EAS®-HT safety clutches do not require special maintenance work. They are largely protected against dust and humidity, they have an initial grease filling and are therefore mainly maintenance-free.

EAS®-elements Please find a detailed description in the respective Installation and Operational Instructions (go to www.mayr.com). Special maintenance work may be necessary, however, if the device is subject to large amounts of dirt or dust or is operating in extreme ambient conditions.

In this case, please contact the manufacturer.

#### Mounting onto the shaft:

In a standard delivery, the EAS®-HT safety clutches are delivered with a finish bore and a keyway acc. DIN 6885/1 P9. The clutch can be secured axially onto the shaft e.g. using a washer and a screw, screwed into the shaft threaded centre hole.

Optionally, we deliver a frictionally-locking shaft-hub connection (see EAS $^\circ$ -HT options, page 19).

#### Pre-selection of the clutch

Drive lines in heavy engineering are robust and designed for operation in adverse conditions. In contrast to systems with servomotor-driven drives, the torque course and the system behaviour often cannot be determined precisely.

Frequently, only the drive power of the motor and the permitted max. torque of the gear output are known.

Using tried-and-tested operating factors, clutch sizes suitable for the application can be pre-selected.

#### Pre-selection

$$T_{N} = \frac{9550 \times P}{n}$$
 [Nm]

$$T_{G} \approx T_{N} \times K_{B}$$
 [Nm]

Names	Names:				
T <sub>N</sub>	[Nm]	Nominal torque of the motor			
T <sub>G</sub>	[Nm]	Pre-selected release torque on the overload clutch			
Р	[KW]	Input power motor			
n	[rpm]	Speed			
K <sub>B</sub>	[-]	Service factor			

Service	Service factors:					
2,5 - 3	medium impacts	Stirring units / pumps (viscid fluids) / kneading machines / mixing systems / conveyor belts / etc.				
3 - 5	high impacts	Shredding machines / centrifuges / crushers / roll trains / construction machines / mining machines / etc.				

In normal operation, the EAS®-HT transmits the set overload torque via positive locking. All torques for normal operation, including torque peaks, must be transmitted safely and must not cause the safety clutch to respond.

Often, the actual complex of loads (impacts) during operation (e.g. for shredding machines / mixers) are not known and can only be measured in the system with great effort.

Using software specially developed for the purpose, it is possible to simulate the behaviour in case of collisions of such drive lines. The prerequisite is that all specifications are known:

- Mass moments of inertia
- ☐ Rigidities of all overload elements, including the overload clutch
- Parameters of the motor and the control circuit



Particularly in case of load-side vibration generation (e.g. piston compressors / shredding machines / etc.) or alternating torques **please contact us** to select a reliable, tried and tested overload protection for your production systems.

Here, the overload clutch is combined with suitable clutches, depending on the application:

- □ Elastomer coupling
- ☐ Shaft Couplings
- ☐ Curved-tooth coupling

Profit from our many years of market and application experience in different branches.



Misalignment compensation capability of the different shaft misalignment compensation couplings

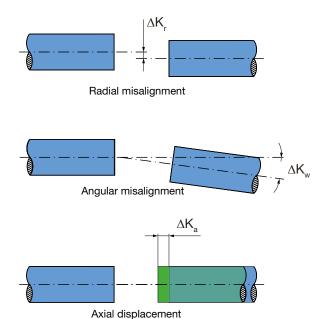


Fig. 4

#### **Shaft Misalignment**

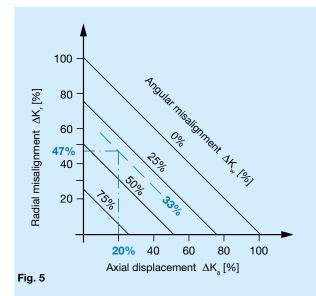
Misalignments between shafts occur due to manufacturing and assembly tolerances, bearing backlash and temperature influences.

This can cause axial, radial and angular shaft misalignment.

The shaft misalignment compensation coupling of the EAS®-HT safety clutch can compensate for misalignments.

The misalignment possibilities of the shaft misalignment compensation coupling are general guideline values (see table "Technical Data").

In the application, the aim is to produce as precise a shaft alignment as possible, so that the bearing loads are reduced to a minimum.



If more than one kind of misalignment takes place simultaneously, they influence each other. The permitted misalignment values are dependent on one another. The sum total of the actual misalignments – in percent of the maximum value – must not exceed 100 %.

#### Example:

EAS®-HT lastic, Size 8 Type 4053.00400.0

- ☐ Axial displacement occurrence:  $\Delta K_a = 0.5$  mm; equals 20 % of the permitted maximum value $\Delta K_a = 2.5$  mm
- ☐ Angular misalignment occurrence:  $\Delta K_w = 0.1$  mm, equals 33 % of the permitted maximum value  $\Delta K_w = 0.3$  mm
- ☐ Radial displacement occurrence:  $\Delta K_w = 0.14$  mm, equals 47 % of the permitted maximum value  $\Delta K_w = 0.3$  mm

# **Product Summary**

## **Safety Clutches/Overload Clutches**

■ EAS®-Compact®/EAS®-NC

Positive locking and completely backlash-free torque limiting clutches

EAS®-smartic®

Cost-effective torque limiting clutches, quick installation

■ EAS®-element clutch/EAS®-elements

Load-disconnecting protection against high torques

■ EAS®-axial

Exact limitation of tensile and compressive forces

EAS®-Sp/EAS®-Sm/EAS®-Zr

Load-disconnecting torque limiting clutches with switching function

ROBA®-slip hub

Load-holding, frictionally locked torque limiting clutches

ROBA®-contitorque

Magnetic continuous slip clutches

■ EAS®-HSC/EAS®-HSE

High-speed safety clutches for high-speed applications

# **Shaft Couplings**

smartflex®/primeflex®

Perfect precision couplings for servo and stepping motors

■ ROBA®-ES

Backlash-free and damping for vibration-sensitive drives

ROBA®-DS/ROBA®-D

Backlash-free, torsionally rigid all-steel couplings

■ ROBA®-DSM

Cost-effective torque-measuring couplings



# **Electromagnetic Brakes/Clutches**

■ ROBA-stop® standard

Multifunctional all-round safety brakes

■ ROBA-stop®-M motor brakes

Robust, cost-effective motor brakes

ROBA-stop®-S

Water-proof, robust monoblock brakes

■ ROBA-stop®-Z/ROBA-stop®-silenzio®

Doubly safe elevator brakes

ROBA®-diskstop®

Compact, very quiet disk brakes

ROBA®-topstop®

Brake systems for gravity loaded axes

■ ROBA®-linearstop

Backlash-free brake systems for linear motor axes

ROBA®-guidestop

Backlash-free holding brake for profield rail guides

□ ROBATIC®/ROBA®-quick/ROBA®-takt

Electromagnetic clutches and brakes, clutch brake units



tendo®-PM

Permanent magnet-excited DC motors







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You can find the complete address for the representative responsible for your area under www.mayr.com in the internet.  $\stackrel{\curvearrowright}{\sim}$ 

2/05/2015 GF/SU/SC